

Figure A36-10. Correspondence between measured and reference flight paths for the application of the integrated method of adjustment

(1) XY represents the portion of the measured flight path that includes the noise time history relevant to the calculation of flyover and approach EPNL; X,Y, represents the corresponding reference flight path.

(2) The points Q_0 , Q_1 , Q_n represent airplane positions on the measured flight path at time t_0 , t_1 and t_n respectively. Point Q_1 is the point at which the noise was emitted and observed as one-third octave values SPL(i)1 at the noise measuring station K at time t₁. Point Q_{r1} represents the corresponding position on the reference flight path for noise observed as SPL(i)_{rl} at the reference measuring station K_r at time t_{r1} . Q_1K and $Q_{r1}K_r$ are respectively the measured and reference noise propagation paths, which in each case form the angle θ_1 with their respective flight paths. Q_{r0} and Q_{rn} are similarly the points on the reference flight path corresponding to Q_0 and Q_n on the measured flight path. Q_0 and Q_n are chosen so that between Q_{r0} and Q_{rn} all values of PNLT_r (computed as described in paragraphs A36.9.4.2.2 and A36.9.4.2.3) within 10 dB of the peak value are included.

(b) The portions of the test flight path and the reference flight path described in paragraph (b)(1) and (2), and illustrated in Figure A36-11(a) and (b), include the noise time history that is relevant to the calculation of lateral EPNL.

- (1) In figure A36–11(a) XY represents the portion of the measured flight path that includes the noise time history that is relevant to the calculation of lateral EPNL; in figure A36–11(b), X_rY_r represents the corresponding portion of the reference flight path.
- (2) The points Q_0 , Q_1 and Q_n represent airplane positions on the measured flight path at time t_0 , t_1 and t_n respectively. Point Q_1 is the point at which the noise was emitted and observed as one-third octave values $SPL(i)_1$ at the noise measuring station K at time t_1 . The point Q_r represents the corresponding position on the reference flight path for noise observed as $SPL(i)_{r1}$ at the measuring station K_r at time t_{r1} . Q_1K and $Q_{r1}K_r$ are respectively the measured and reference noise propagation paths. Q_{r0} and Q_{rn} are similarly the points on the reference flight path corresponding to Q_0 and Q_n on the measured flight path.