1.j.3	Balked Landing	Airspeed—±3 kts, Altitude— ±20 ft. (6.1m), Torque— ±3%, Rotor Speed—±1.5%, Pitch Attitude—±1.5°, Bank Attitude—±1.5°, Heading— ±2°, Longitudinal Control Position—±10%, Lateral Control Position—±10%, Directional Control Posi- tion—±10%, Collective Control Position—±10%.	Approach	Record the results for the maneuver initiated from a stabilized approach at the landing decision point (LDP).	x	x	x	
1.j.4	Autorotational Landing.	Torque—±3%, Rotor Speed—±3%, Vertical Ve- locity—±100 fpm (0.50m/ sec) or 10%, Pitch Atti- tude—±2°, Bank Attitude— ±2°, Heading—±5°, Longi- tudinal Control Position— ±10%, Lateral Control Posi- tion—±10%, Directional Control Position—±10%, Collective Control Posi- tion—±10%.	Landing	Record the results of an autorotational deceleration and landing from a sta- bilized autorotational de- scent, to touch down. If flight test data containing all required parameters for a complete power-off land- ing is not available from the aircraft manufacturer for this test and other quali- fied flight test personnel are not available to acquire this data, the sponsor may coordinate with the NSPM to determine if it is appro- priate to accept alternative testing means.		x	x	Alternative approaches for acquiring this data may be acceptable, depending on the aircraft as well as the personnel and the data re- cording, reduction, and in- terpretation facilities to be used, are: (1) a simulated autorotational flare and re- duction of rate of descent (ROD) at altitude; or (2) a power-on termination fol- lowing an autorotational approach and flare.

2. Handling Qualities

 2.a.
 Control System Mechanical Characteristics

 For simulators requiring Static or Dynamic tests at the controls (i.e., cyclic, collective, and pedal), special test fixtures will not be required during initial or upgrade evaluations if the sponsor's QTG/MQTG shows both test fixture results and the results of an alternative approach, such as computer plots produced concurrently showing satisfactory agreement. Repeat of the alternative method during the initial or upgrade evaluation satisfies this test requirement. For initial and upgrade evaluations, the

control dynamic characteristics must be measured at and recorded directly from the flight deck controls, and must be accomplished in hover, climb, cruise, and autorotation.

Contact the NSPM for clarification of any issue regarding helicopters with reversible controls or where the required validation data is not attainable.

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